

# RADAR Titan Flyby during S75/T86

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- Sequence: s75
- Rev: 172
- Observation Id: t86
- Target Body: Titan
- Data Take Number: 243
- PDT Config File: S75\_sip\_psiv\_120710\_pdt.cfg
- SMT File: s75\_20120614.smt
- PEF File: z0750e\_GH.pef

## 1 Introduction

This memo describes the Cassini RADAR activities for the T86 Titan flyby. This SAR data collection occurs during the S75 sequence of the Saturn Tour. This is a partial radar pass with ride-along SAR inbound imaging in the north polar area partially overlapping T16, crossing the ends of T16, T19, T30 and T44. A sequence design memo provides the science context of the scheduled observations, an overview of the pointing design, and guidelines for preparing the RADAR IEB.

## 2 CIMS and Division Summary

| CIMS ID                  | Start             | End               | Duration  | Comments |
|--------------------------|-------------------|-------------------|-----------|----------|
| 172TL_T86WARMUP001_RIDER | 2012-270T05:35:38 | 2012-270T14:17:38 | 08:42:0.0 |          |
| 172TL_T86RASAR001_PRIME  | 2012-270T14:17:38 | 2012-270T14:30:38 | 00:13:0.0 |          |
| 172TL_T86RASAR002_PRIME  | 2012-270T14:30:38 | 2012-270T14:40:38 | 00:10:0.0 |          |
| 172TL_T86RASAR003_PRIME  | 2012-270T14:40:38 | 2012-270T14:53:38 | 00:13:0.0 |          |
| 172TL_T86OUTALT001_PRIME | 2012-270T14:53:38 | 2012-270T15:10:38 | 00:17:0.0 |          |

Table 1: t86 CIMS Request Sequence

Each RADAR observation is represented to the project by a set of requests in the Cassini Information Management System (CIMS). The CIMS database contains requests for pointing control, time, and data volume. The CIMS requests show a high-level view of the sequence design. Table 1 shows the CIMS request summary for this observation.

| Division | Name                            | Start      | Duration   | Data Vol | Comments                          |
|----------|---------------------------------|------------|------------|----------|-----------------------------------|
| a        | Warmup                          | -9:00:0.0  | 08:37:0.0  | 7.7      | Warmup                            |
| b        | standard_radiometer_inbound     | -0:23:0.0  | 00:03:30.0 | 0.2      | radiometer off-target             |
| c        | standard_sar_hi                 | -0:19:30.0 | 00:01:0.0  | 2.4      | Inbound SAR imaging               |
| d        | standard_sar_hi                 | -0:18:30.0 | 00:07:0.0  | 18.9     | Inbound SAR imaging               |
| e        | standard_sar_hi                 | -0:11:30.0 | 00:01:12.0 | 3.2      | SAR Turn transition, beam 3 only  |
| f        | standard_sar_hi                 | -0:10:18.0 | 00:01:6.0  | 3.0      | SAR Turn transition, beam 3 only  |
| g        | standard_sar_hi                 | -0:09:12.0 | 00:01:42.0 | 4.6      | SAR Turn transition, beam 3 only  |
| h        | standard_sar_hi                 | -0:07:30.0 | 00:02:30.0 | 6.8      | SAR Turn transition, beam 3 only  |
| i        | standard_sar_hi                 | -0:05:0.0  | 00:10:0.0  | 127.8    | Hi-SAR Main Swath                 |
| j        | standard_sar_hi                 | 00:05:0.0  | 00:02:30.0 | 6.8      | SAR Turn transition, beam 3 only  |
| k        | scatterometer_compressed        | 00:07:30.0 | 00:15:0.0  | 2.7      | Compressed Scatt/Rad off-target   |
| l        | scatterometer_imaging           | 00:22:30.0 | 00:01:18.0 | 4.7      | Scatterometer imaging during turn |
| m        | standard_scatterometer_outbound | 00:23:48.0 | 00:00:4.0  | 0.6      | Atmospheric Probe with Tone       |
| n        | standard_scatterometer_outbound | 00:23:52.0 | 00:00:2.0  | 0.3      | Atmospheric Probe with Chirp      |
| o        | standard_altimeter_outbound     | 00:23:54.0 | 00:04:6.0  | 8.1      | Outbound altimetry                |
| p        | standard_radiometer_outbound    | 00:28:0.0  | 00:07:0.0  | 0.4      | Outbound radiometry               |
| Total    |                                 |            |            | 198.1    |                                   |

Table 2: Division summary. Data volumes (Mbits) are estimated from maximum data rate and division duration.

| Div | Alt (km) | Slant range (km) | B3 Size (target dia) | B3 Dop. Spread (Hz) |
|-----|----------|------------------|----------------------|---------------------|
| a   | 175430   | off target       | 0.22                 | off target          |
| b   | 5948     | off target       | 0.01                 | off target          |
| c   | 4897     | off target       | 0.01                 | off target          |
| d   | 4604     | 5724             | 0.01                 | 1249                |
| e   | 2684     | 3323             | 0.01                 | 1705                |
| f   | 2391     | 2601             | 0.01                 | 1805                |
| g   | 2137     | 2329             | 0.01                 | 1902                |
| h   | 1778     | 2450             | 0.01                 | 2059                |
| i   | 1343     | 1753             | 0.00                 | 2288                |
| j   | 1343     | 1753             | 0.00                 | 2288                |
| k   | 1778     | 3072             | 0.01                 | 2060                |
| l   | 5796     | 6436             | 0.01                 | 1071                |
| m   | 6192     | 6192             | 0.01                 | 1023                |
| n   | 6212     | 6212             | 0.01                 | 1020                |
| o   | 6222     | 6222             | 0.01                 | 1019                |
| p   | 7491     | 7491             | 0.01                 | 891                 |

Table 3: Division geometry summary. Values are computed at the start of each division. B3 Doppler spread is for two-way 3-dB pattern. B3 size is the one-way 3-dB beamwidth

Although the CIMS requests show Low-SAR intervals, in reality the radar will be operated in Hi-SAR mode through most of this flyby.

The CIMS requests form the basis of a pointing design built using the project pointing design tool (PDT). The details of the pointing design are shown by the PDT plots on the corresponding tour sequence web page. (See <https://cassini.jpl.nasa.gov/radar>.) The RADAR pointing sequence is ultimately combined with pointing sequences from other instruments to make a large merged c-kernel. C-kernels are files containing spacecraft attitude data.

A RADAR tool called RADAR Mapping and Sequencing Software (RMSS) reads the merged c-kernel along with other navigation data files, and uses these data to produce a set of instructions for the RADAR observation. The RADAR instructions are called an Instrument Execution Block (IEB). The IEB is produced by running RMSS with a radar config file that controls the process of generating IEB instructions for different segments of time. These segments of time are called divisions with a particular behavior defined by a set of division keywords in the config file. Table 2 shows a summary of the divisions used in this observation. Table 3 shows a summary of some key geometry values for each division.

### 3 Overview

T86 is a partial pass. The observation starts with 3 scan lines providing beam 3 only SAR imaging of the northern polar seas and covers a region overlapping part of the T64 SAR swath. Following this, additional beam 3 only SAR imaging is performed while turning onto a ride-along SAR swath around closest approach. Ride-along SAR swaths are collected when INMS is the prime instrument and the spacecraft X-axis is maintained in the direction of motion. The radar operates by pointing the -Z axis at Titan to the extent possible, and collecting data while the beams stay on target. After the ride-along imaging, the radar switches to compressed scatterometry mode to reduce data usage while turning off target and eventually back on target for an altimeter track. During the turn back on target, some scatterometer mode imaging data is collected. The radar data collection then ends with a normal outbound altimeter segment including atmospheric probe measurements at the start of the nadir pointing track.

## 4 Mode Specific Operation and Performance

Many details of standard radar sequencing during the 4 main modes (Radiometry, Scatterometry, Altimetry, and SAR) have been discussed in previous sequence memos for prior observations. Refer to these for details. Some select performance highlights are illustrated in figures and explained in the following subsections.

### 4.1 SAR Resolution Performance

For all of the SAR divisions the effective resolution can be calculated from the same equations used in the high-altitude imaging discussion. Figure 1 shows the results from these equations using the parameters from the IEB as generated by RMSS. The calculations are performed for the boresight of beam 3 which is the center of the swath.

Projected range increases with decreasing incidence angle, so the range resolution varies across the swath with better resolution at the outer edge. The SAR pointing profile decreases the incidence angle as time progresses and altitude increases, so there is progressive deterioration of range resolution away from closest approach. The projected range resolution rapidly deteriorates as the incidence angle decreases toward zero at the very beginning and end of the swath.

Azimuth resolution is a function of the synthetic aperture size which is determined by the length of the receive window in each burst (assuming the receive window is always filled with echos). Azimuth resolution deteriorates less quickly because the number of pulses and the length of the receive window are increased as altitude increases which mitigates the increasing doppler bandwidth of the beam patterns. The receive window length increases to fill the round trip time until the science data buffer is filled. At this point it is no longer possible to extend the receive window, and azimuth resolution starts to deteriorate more rapidly.

## 5 Revision History

1. June 13, 2013: Final release

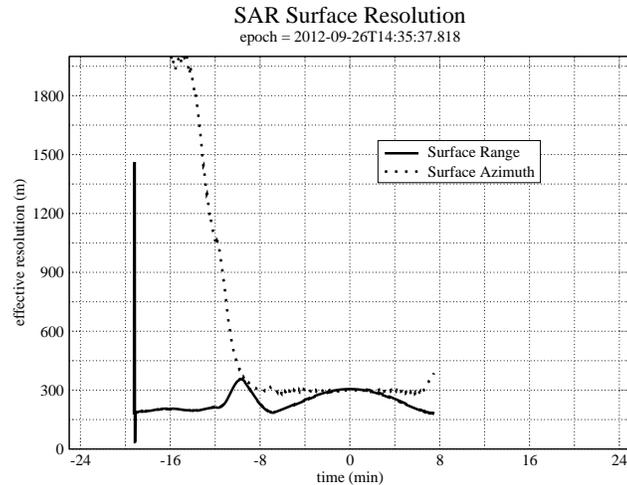


Figure 1: SAR projected range and azimuth resolution. These values are computed from the IEB parameters and are not related to the pixel size in the BIDR file. The pixel size was selected to be always smaller than the real resolution.

## 6 Acronym List

|         |   |
|---------|---|
| ALT     | Altimeter - one of the radar operating modes  |
| BAQ     | Block Adaptive Quantizer  |
| CIMS    | Cassini Information Management System - a database of observations                                  |
| Ckernel | NAIF kernel file containing attitude data   |
| DLAP    | Desired Look Angle Profile - spacecraft pointing profile designed for optimal SAR performance       |
| ESS     | Energy Storage System - capacitor bank used by RADAR to store transmit energy                       |
| IEB     | Instrument Execution Block - instructions for the instrument  |
| ISS     | Imaging Science Subsystem   |
| IVD     | Inertial Vector Description - attitude vector data  |
| IVP     | Inertial Vector Propagator - spacecraft software, part of attitude control system                   |
| INMS    | Inertial Neutral Mass Spectrometer - one of the instruments   |
| NAIF    | Navigation and Ancillary Information Facility   |
| ORS     | Optical Remote Sensing instruments  |
| PDT     | Pointing Design Tool  |
| PRI     | Pulse Repetition Interval   |
| PRF     | Pulse Repetition Frequency  |
| RMSS    | Radar Mapping Sequencing Software - produces radar IEB's  |
| SAR     | Synthetic Aperture Radar - radar imaging mode   |
| SNR     | Signal to Noise Ratio   |
| SOP     | Science Operations Plan - detailed sequence design  |
| SOPUD   | Science Operations Plan Update - phase of sequencing when SOP is updated prior to actual sequencing |
| SSG     | SubSequence Generation - spacecraft/instrument commands are produced                                |
| SPICE   | Spacecraft, Instrument, C-kernel handling software - supplied by NAIF to use NAIF kernel files.     |
| TRO     | Transmit Receive Offset - round trip delay time in units of PRI                                     |