RADAR Titan Flyby during S46/T48

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- Sequence: s46
- Rev: 095
- Observation Id: t48
- Target Body: Titan
- Data Take Number: 174
- PDT Config File: S46_ssup_psiv1_080929_pdt.cfg
- SMT File: S46_SMT_080923.rpt
- PEF File: z0460c.pef

1 Introduction

This memo describes the Cassini RADAR activities for the T48 Titan flyby. This SAR data collection occurs during the S46 sequence of the Saturn Tour. This is a partial radar pass with normal SAR inbound imaging and ride-along outbound imaging. The SAR profile is pushbroomed on the inbound side. A sequence design memo provides the science context of the scheduled observations, an overview of the pointing design, and guidlines for preparing the RADAR IEB.

2 CIMS and Division Summary

CIMS ID	Start	End	Duration	Comments
095TI_T48WARMUP001_RIDER	2008-340T05:10:45	2008-340T13:35:45	08:25:0.0	Warmup for T48.
095TI_T48IHISAR001_PRIME	2008-340T13:35:45	2008-340T13:55:45	00:20:0.0	
095TI_T48INALT001_PRIME	2008-340T13:55:45	2008-340T14:07:45	00:12:0.0	
095TI_T48INSAR001_PRIME	2008-340T14:07:45	2008-340T14:20:45	00:13:0.0	
095TI_T48RASAR001_PRIME	2008-340T14:20:45	2008-340T14:47:40	00:26:55.0	

Table 1: t48 CIMS Request Sequence

Each RADAR observation is represented to the project by a set of requests in the Cassini Information Management System (CIMS). The CIMS database contains requests for pointing control, time, and data volume. The CIMS requests show a high-level view of the sequence design. Table 1 shows the CIMS request summary for this observation.

Division	Name	Start	Duration	Data Vol	Comments
a	Warmup	-9:12:0.0	04:28:0.0	4.0	Warmup
b	standard_radiometer_inbound	-4:44:0.0	03:59:42.0	14.3	Inbound radiometry scans
c	standard_scatterometer_inbound	-0:44:18.0	00:01:6.0	2.0	Inbound scatterometry during turn to high alt imaging
d	scatterometer_imaging	-0:43:12.0	00:04:18.0	16.8	Inbound scatterometer imaging
e	scatterometer_imaging	-0:38:54.0	00:01:6.0	4.3	Inbound scatterometer imaging
f	scatterometer_imaging	-0:37:48.0	00:01:30.0	5.8	Inbound scatterometer imaging
g	scatterometer_imaging	-0:36:18.0	00:02:6.0	8.2	Inbound scatterometer imaging
h	scatterometer_imaging	-0:34:12.0	00:01:36.0	6.2	Inbound scatterometer imaging
i	standard_sar_low	-0:32:36.0	00:02:48.0	16.8	Inbound SAR-Low
j	standard_scatterometer_inbound	-0:29:48.0	00:01:0.0	1.8	Inbound scatterometry during turn to alt
k	standard_altimeter_inbound	-0:28:48.0	00:09:0.0	16.2	Inbound altimetry
l	standard_scatterometer_inbound	-0:19:48.0	00:00:2.0	0.3	Atmospheric Probe with Chirp
m	standard_scatterometer_inbound	-0:19:46.0	00:00:2.0	0.3	Atmospheric Probe with Tone
n	standard_sar_hi	-0:19:44.0	00:01:8.0	7.5	Hi-SAR Turn transition, beam 3 only
o	standard_sar_pingpong	-0:18:36.0	00:02:36.0	36.8	Inbound ping-pong
p	standard_sar_hi	-0:16:0.0	00:09:0.0	127.4	Inbound startdard Hi-SAR
q	standard_sar_hi	-0:07:0.0	00:03:0.0	19.8	Inbound startdard Hi-SAR
r	standard_sar_hi	-0:04:0.0	00:08:0.0	113.3	Hi-SAR Main Swath
s	standard_sar_hi	00:04:0.0	00:02:30.0	16.5	Outbound startdard Hi-SAR
t	standard_radiometer_outbound	00:06:30.0	00:15:30.0	0.9	Outbound radiometry scans
Total				419.2	

Table 2: Division summary. Data volumes (Mbits) are estimated from maximum data rate and division duration.

Div	Alt (km)	Slant range (km)	B3 Size (target dia)	B3 Dop. Spread (Hz)
a	191689	off target	0.24	off target
b	97997	off target	0.13	off target
c	13739	15082	0.02	612
d	13357	13667	0.02	625
e	11867	12806	0.02	685
f	11487	12718	0.02	702
g	10969	12070	0.02	727
h	10247	10874	0.02	766
i	9699	10119	0.02	799
j	8744	8959	0.01	863
k	8405	8405	0.01	889
l	5418	5418	0.01	1210
m	5407	5407	0.01	1211
n	5396	5396	0.01	1213
o	5033	5170	0.01	1270
p	4218	4318	0.01	1419
q	1782	2079	0.01	2204
r	1248	1639	0.00	2510
s	1248	1563	0.00	2510
t	1678	2837	0.01	2257

Table 3: Division geometry summary. Values are computed at the start of each division. B3 Doppler spread is for two-way 3-dB pattern. B3 size is the one-way 3-dB beamwidth

Although the CIMS requests show Low-SAR intervals, in reality the radar will be operated in Hi-SAR mode through most of this flyby.

The CIMS requests form the basis of a pointing design built using the project pointing design tool (PDT). The details of the pointing design are shown by the PDT plots on the corresponding tour sequence web page. (See https://cassini.jpl.nasa.gov/radar.) The RADAR pointing sequence is ultimately combined with pointing sequences from other instruments to make a large merged c-kernel. C-kernels are files containing spacecraft attitude data.

A RADAR tool called RADAR Mapping and Sequencing Software (RMSS) reads the merged c-kernel along with other navigation data files, and uses these data to produce a set of instructions for the RADAR observation. The RADAR instructions are called an Instrument Execution Block (IEB). The IEB is produced by running RMSS with a radar config file that controls the process of generating IEB instructions for different segments of time. These segments of time are called divisions with a particular behavior defined by a set of division keywords in the config file. Table 2 shows a summary of the divisions used in this observation. Table 3 shows a summary of some key geometry values for each division.

3 Overview

T48 has a high altitude imaging segment. Inbound Hi-SAR consists of two scan lines over the southern hemisphere near T36 ridealong . The outbound imaging is right looking with an incidence angle offset to cover Tui Regio. At the end of the inbound altimetry, two short observations in scatterometry mode are inserted to look for echo energy coming back from the atmosphere. The very end of the nadir pointed boresight time is used for this observation because it minimizes the intrusion of surface echo power and maximizes SNR due to the low range.

4 Mode Specific Operation and Performance

Many details of standard radar sequencing during the 4 main modes (Radiometry, Scatterometry, Altimetry, and SAR) have been discussed in previous sequence memos for prior observations. Refer to these for details. Some selecte

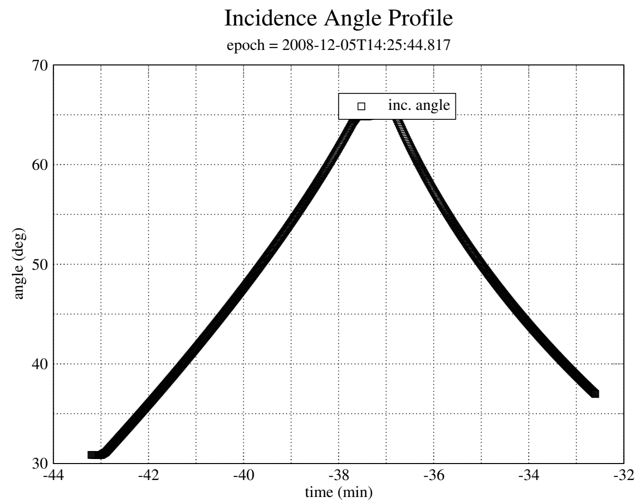

Figure 1: Incidence angle variation during Inbound scatterometer imaging.

performance highlights are illustrated in figures and explained in the following subsections.

4.1 High Altitude Imaging

The high altitude imaging segments are designed to optimize range-doppler ambiguities, resolution, number of looks and noise-equivalent cross-section. These segments push against the 7% duty cycle limit, the 32 Kbyte size of the science data buffer, the round trip time limitation, and the number of pulses that the ESS can put out. To allow the best possible azimuth resolution, the duty cycle is reduced to allow a longer pulse train while still remaining below the 7% duty cycle limit. This trades SNR for resolution as was done in T19. Resolution in these segments will be in the 1 to 2 km range. For more technical details on range and doppler ambiguities, refer to the discussion in the T19 sequence design memo.

4.2 SAR-style Scatterometer Resolution Performance

Since SAR processing will be applied to this segment, the effective resolution can be calculated from the same equations,

$$\delta R_g = \frac{c}{2B_r \sin\theta_i}, \tag{1}$$

$$\delta x = \frac{\lambda R}{2\tau_{rw} v \sin\theta_v}, \tag{2}$$

where δR_g is the projected range resolution on the surface, c is the speed of light, B_r is the transmitted chirp bandwidth, θ_i is the incidence angle, δx is the azimuth resolution on the surface, λ is the transmitted wavelength, R is the slant range, τ_{rw} is the length of the receive window, v is the magnitude of the spacecraft velocity relative to the target body, and θ_v is the angle between the velocity vector and the look direction. Figure 2 shows the results from these equations for the scatterometer imaging time. The calculations are performed for the boresight of beam 3 which is the center of the swath.

4.3 SAR Resolution Performance

For all of the SAR divisions the effective resolution can be calculated from the same equations used in the high-altitude imaging discussion. Figure 5 shows the results from these equations using the parameters from the IEB as generated by RMSS. The calculations are performed for the boresight of beam 3 which is the center of the swath.

Projected range increases with decreasing incidence angle, so the range resolution varies across the swath with better resolution at the outer edge. The SAR pointing profile decreases the incidence angle as time progresses and

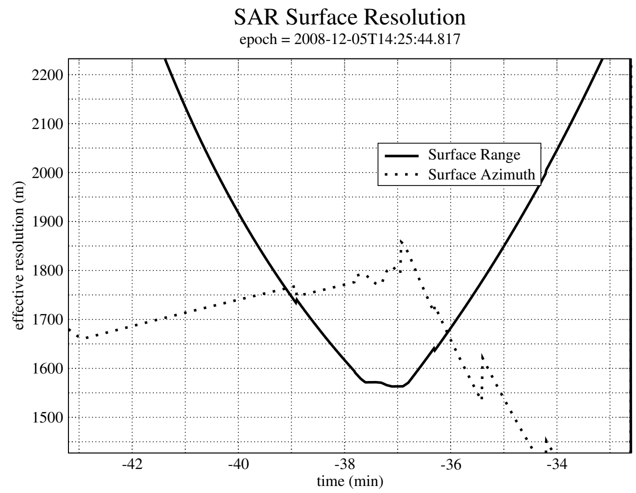

Figure 2: Inbound Scatterometer imaging projected range and azimuth resolution. These values are computed from the IEB parameters.

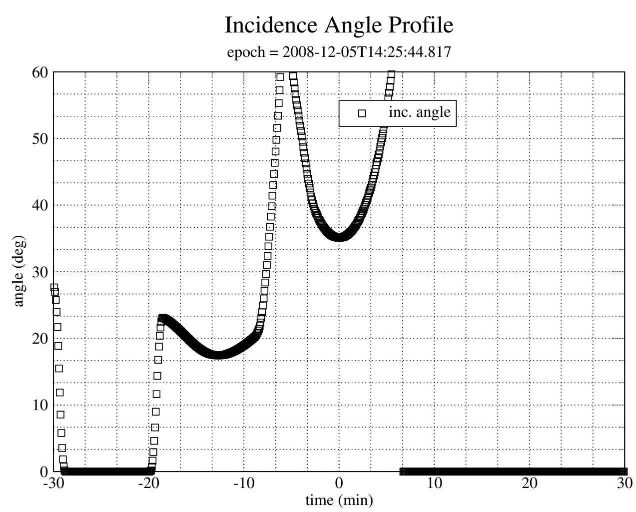

Figure 3: B3 boresight incidence angle during the time around c/a.

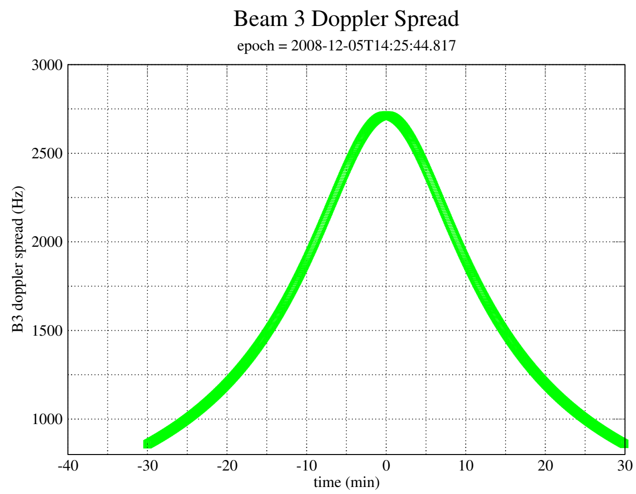

Figure 4: Nadir pointed B3 doppler spread during the time around c/a. Doppler spread is measured within the two-way 3 dB beam pattern.

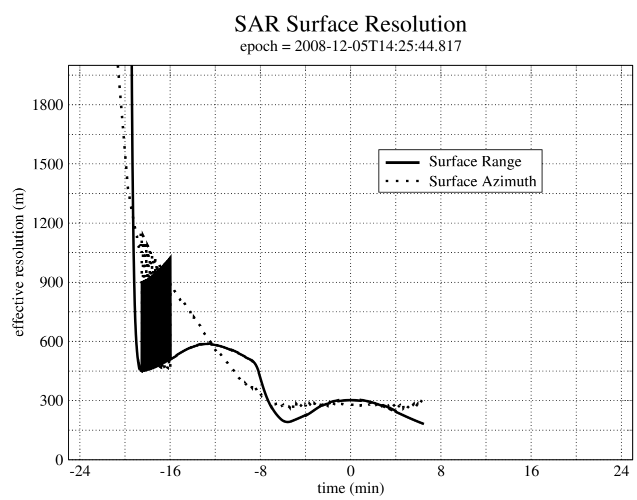

Figure 5: SAR projected range and azimuth resolution. These values are computed from the IEB parameters and are not related to the pixel size in the BIDR file. The pixel size was selected to be always smaller than the real resolution.

altitude increases, so there is progressive deterioration of range resolution away from closest approach. The projected range resolution rapidly deteriorates as the incidence angle decreases toward zero at the very beginning and end of the swath.

Azimuth resolution is a function of the synthetic aperture size which is determined by the length of the receive window in each burst (assuming the receive window is always filled with echos). Azimuth resolution deteriorates less quickly because the number of pulses and the length of the receive window are increased as altitude increases which mitigates the increasing doppler bandwidth of the beam patterns. The receive window length increases to fill the round trip time until the science data buffer is filled. At this point it is no longer possible to extend the receive window, and azimuth resolution starts to deteriorate more rapidly.

4.4 Atmospheric Probe

Atmospheric probe measurements were inserted to look for signals from preciptation above the surface. Details are provided in prior sequence memos starting with T30.

5 Revision History

1. Feb 25, 2009: Final release

6 Acronym List

ALT	Altimeter - one of the radar operating modes
BAQ	Block Adaptive Quantizer
CIMS	Cassini Information Management System - a database of observations
Ckernel	NAIF kernel file containing attitude data
DLAP	Desired Look Angle Profile - spacecraft pointing profile designed for optimal SAR performance
ESS	Energy Storage System - capacitor bank used by RADAR to store transmit energy
IEB	Instrument Execution Block - instructions for the instrument
ISS	Imaging Science Subsystem
IVD	Inertial Vector Description - attitude vector data
IVP	Inertial Vector Propagator - spacecraft software, part of attitude control system
INMS	Inertial Neutral Mass Spectrometer - one of the instruments
NAIF	Navigation and Ancillary Information Facility
ORS	Optical Remote Sensing instruments
PDT	Pointing Design Tool
PRI	Pulse Repetition Interval
PRF	Pulse Repetition Frequency
RMSS	Radar Mapping Sequencing Software - produces radar IEB's
SAR	Synthetic Aperture Radar - radar imaging mode
SNR	Signal to Noise Ratio
SOP	Science Operations Plan - detailed sequence design
SOPUD	Science Operations Plan Update - phase of sequencing when SOP is updated prior to actual sequencing
SSG	SubSequence Generation - spacecraft/instrument commands are produced
SPICE	Spacecraft, Instrument, C-kernel handling software - supplied by NAIF to use NAIF kernel files.
TRO	Transmit Receive Offset - round trip delay time in units of PRI